

Prospects of Real-time Satellite Positioning using EPN Resources

W. Söhne¹⁾, A. Stürze¹⁾, G. Weber¹⁾, L. Mervart²⁾ ¹⁾Federal Agency for Cartography and Geodesy, Frankfurt am Main, Germany ²⁾Technical University of Prague, Czech Republic





MotivationIGS-RT PP

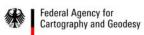
Standardization efforts

- Real-time concept
 - BKG Ntrip Server (BNS)
 - BKG Ntrip Client (BNC)
 - GNSS processing engine
- First results
 - Single Point Positioning
 - Zenith Total Delay parameters

Conclusions and outlook

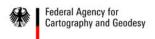


- GNSS real-time data streaming has been successfully developed within EUREF
- Special Project "EUREF-IP" was created in 2002
- Currently ~ 90 EPN stations with real-time capability
- SP EUREF-IP moved towards EPN routine operations end of 2007

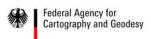


GNSS development has been accelerated

- from daily to hourly files (data)
- from post-processing to near real-time (products)
- Current evolution is going towards
 - Real-time data streaming
 - Real-time monitoring and analysis
- With the improvement of products and models the GNSS analysis has been extended
 - From relative positioning
 - To single point positioning

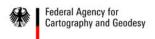


- > Key objectives (selection):
 - RT network
 - Generate RT products
 - Enhancement of (existing) IGS products
 - Investigation of standards and formats
- CfP in June 2007 (IGS mail 5616), see http://www.rtigs.net/pilot/index.php
- > 25 proposals until October 2007
- Decision in December 2007 to accept them all (IGS mail 5692)
- Kickoff in March 2008 (mail by M. Caissy to the participants)



Proposals to the individual categories

- RT tracking stations: 82+ (69+ plus 13 "possibly")
- RT data centers
 - RT data-file centers: 5
 - RT data/product distribution centers: 9
- RT analysis centers: 7 (8)
- RT associate analysis centers: 1
- RT analysis center coordinator: 1 (Loukis Agrotis (ESOC))
- RT network management & monitoring: 7
- RT users: 13



IGS AC workshop 2-6 June 2008 – recommendations for RT issues

- Both NTRIP and UDPRelay will support dissemination of the Pilot Project Real Time products.
- The Pilot Project Analysis and Data Centre participants will initiate a requirements definition phase for formats of all Real Time products that are within the scope of the Pilot Project. It is assumed that the Data Centre participants will also cover the perspective of the User Community.
- A prototype format for orbits and clocks will be developed and hosted by the RT Data Centres. The timescale for this will be compatible with the schedule for the availability of the products (by January 2009 for individual ACs and March 2009 for the combination product).
- The RT Pilot Project will take an active role in the definition of final formats to support our requirements for all RT products, placing emphasis on influencing the evolution of existing international standards and in particular RTCM.
- IGS become a member of RTCM SC 104
- That RINEX 3.0 be used to define RTIGS requirements for streamed data content and observation resolution
- That SP3c and Clock RINEX be used to define RTIGS requirements for streamed content and resolution for state space orbits and clocks

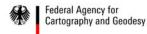


Standardization effort: RTCM

RTCM: Radio Technical Commission for Maritime Services

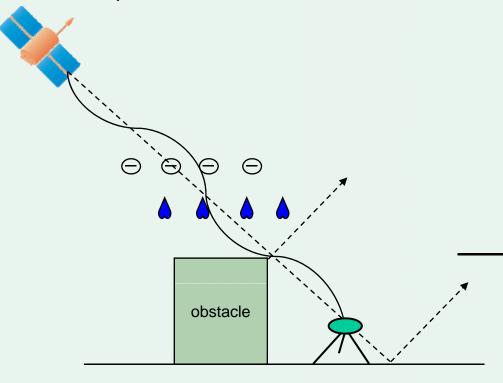
- Founded 1947 as U.S. State Department Advisory Committee
- Now an independent membership organization
- Supports development of standards and regulations
- Runs Special Committees:
 - SC-104 "Differential Global Navigation Satellite Systems"
- and different Working Groups:
 - Communication & data transfer:
 - WG Internet Protocol (e.g., NTRIP 2.0)
 - Modelling:
 - WG RTK Network MSG
 - WG State Space
 - Individual GNSS
 - WG Galileo
 - WG GLONASS
 - WG Version 3 (to accommodate the modernization of existing systems (GPS, GLONASS) and systems under development (EGNOS, Galileo))
 - E.g.: WG Synchronous Messages for Multi-Code/System Operation





WG State Space

- State Space Principle:
 - Provision of information on individual error sources, i.e. "State Space Representation"



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Parameters
Para
State
RTCM

Multipath

Receiver Antenna PCV

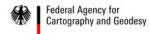
Receiver clock error

Receiver signal delay



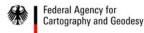
WG State Space

- Additional issues in order to ensure consistent modelling
 - Treatment of site displacements
 - solid earth tides
 - pole tides
 - ocean loading
 - atmospheric loading
 - standardization of tropospheric correction models
 - geodetic datum / coordinate reference systems
 - global, regional and/or local services
 - higher order ionospheric effects
 - satellite attitude models
 - → The IERS conventions can serve as a reference for the standardization.



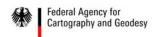
WG State Space

- WG Goal & Schedule:
 - Development of State Space Representation concepts and messages for all types of accuracies, inclusive RTK:
 - 1. Messages for precise orbits and satellite clocks. This is compatible to the basic PPP mode using IGS products. Such messages will enable real time PPP for dual frequency receivers
 - 2. Vertical TEC (VTEC) messages. This will enable RT-PPP for single frequency receivers
 - 3. Slant TEC (STEC) messages, tropospheric messages and satellite signal delay messages. This will enable RTK-PPP

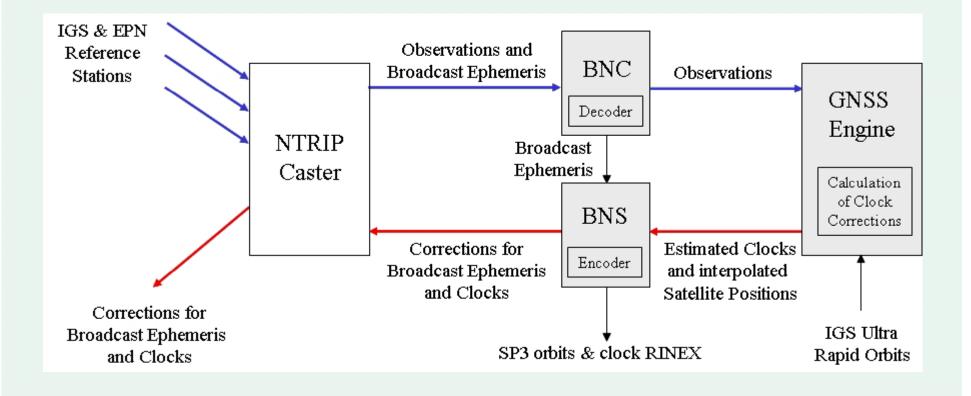


WG State Space

- State Space approach advantages
 - Defining state parameters as corrections to reference parameters or models allows a dramatic reduction of required bandwidth.
 - All or most parameters do not depend on reference station and frequency/signal.
 - Residual local errors of reference stations are eliminated or highly reduced in redundant networks.
 - Missing observations on individual reference stations do not result in missing state space information if the network has enough redundancy.
 - Satellite dependent parameters are globally valid.
 - Atmospheric parameters have global / regional / local validity depending on accuracy level.
 - Orbits and troposphere have high correlation in time, i.e. the update rates can be low.
 - Satellite clocks and ionospheric parameters may require higher update rates.



Orbit & clock correction concept (1)





> Purpose

- Calculate differences between BRDC and IGU orbits in radial, along track and out-of-plane components
- Model orbit differences through polynomials of low degree
- Provide model-based estimations of corrections for BRDC orbits
- Calculate differences between BRDC clocks and improved IGU clocks
- Model clock differences
- Provide model-based estimations of corrections for BRDC clocks

First draft version since April 2008



BKG Ntrip Server (BNS)

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Two data stream inputs necessary via port		
	Start Stop Help=Shift+F1	



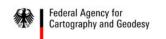
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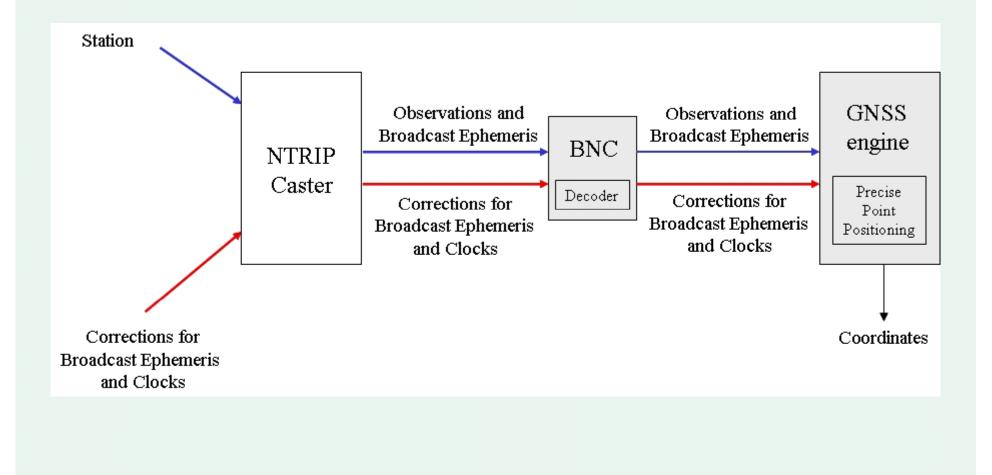


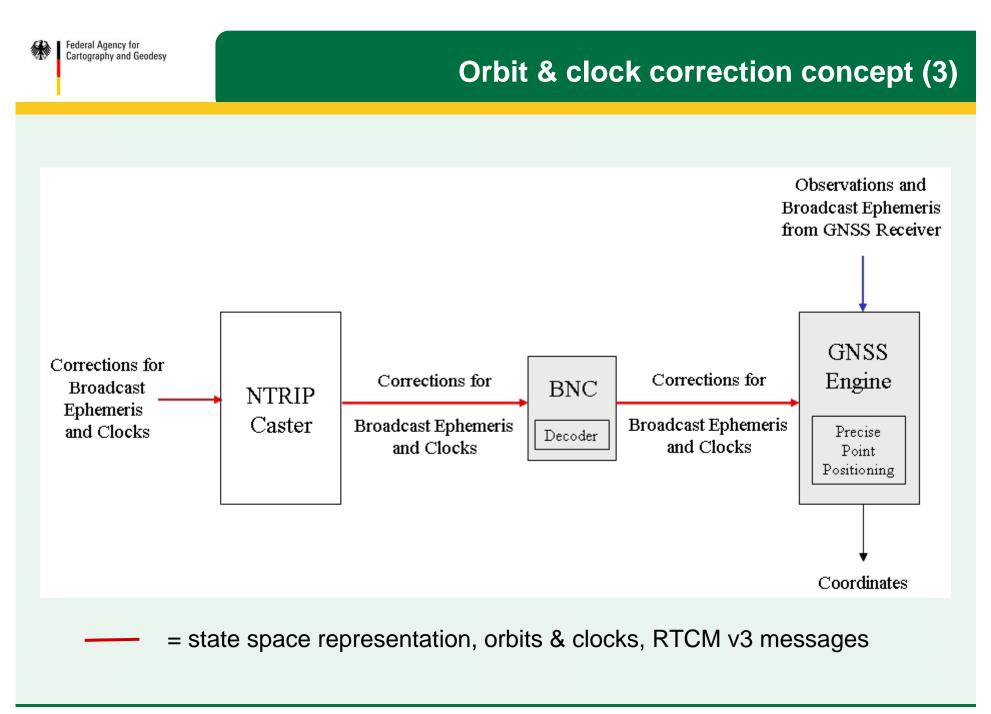
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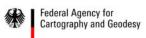
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	Start Stop	Help=Shift+F1	



Orbit & clock correction concept (2)



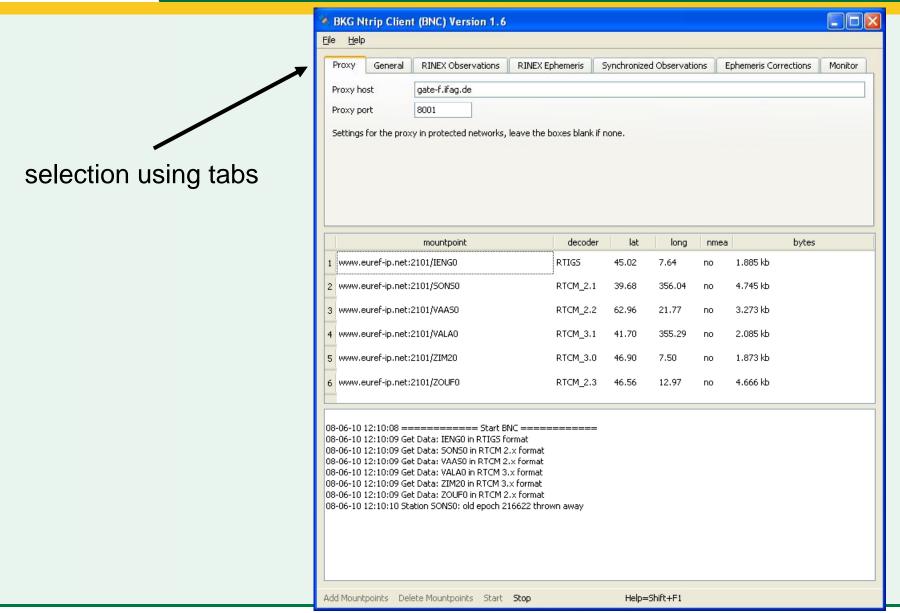




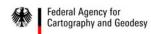
Purpose

- GNSS data streams available through Ntrip
- Generation of high-rate RINEX OBS and NAV files
- Generation of EPH and synchronized OBS via port
- Monitoring of the performance of a real-time network
- Latest version 1.5 available for download since April 2008

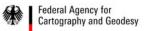




EUREF Symposium, June 18-21 2008, Brussels

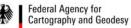


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EURER Symposium, June 10-21 2000, Drussels



Output of synchronized observation via port

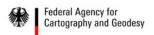
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14	83	2169	960.0	G13	8	1.760	1.771	0.117	0.224	
14	83	2169	960.0	G15	3	0.035	0.110	0.362	0.009	
14	83	2169	960.0	G2 4	46	1.761	1.484	1.553	0.266	
.4	83	2169	960.0	G2 5	106	3.587	0.842	-0.250	0.242	
14	83	2169	960.0	G2 6	70	-16.223	1.179	-0.809	0.198	
.4	83	2169	960.0	G27	31	-0.922	0.806	-2.846	0.990	
14	83	2169	960.0	G28	171	8.477	1.516	-0.337	0.069	
.4	83	2169	960.0	R07	18	-1.204	3.000	0.005	1.871	
14	83	2169	960.0	R08	18	-0.506	3.839	-5.356	2.960	
14	83	2169	960.0	R10	18	-4.353	2.352	4.990	-3.177	
14	83	2169	960.0	R11	10	2.059	37.009	29.719	263.894	
1.0	00	2160	0.00	D17	10	4 150	1 520	2 247	0 770	

	1483 216960.0 G13	8	1.760	1.771	0.117	0.224	
Ephemeris	1483 216960.0 G15	3	0.035	0.110	0.362	0.009	
· ·	1483 216960.0 G24	46	1.761	1.484	1.553	0.266	
corrections can be	1483 216960.0 G25	106	3.587	0.842	-0.250	0.242	
	1483 216960.0 G26	70	-16.223	1.179	-0.809	0.198	
stored in different	1483 216960.0 G27	31	-0.922	0.806	-2.846	0.990	
	1483 216960.0 G28	171	8.477	1.516	-0.337	0.069	
intervals	1483 216960.0 R07	18	-1.204	3.000	0.005	1.871	
	1483 216960.0 R08	18	-0.506	3.839	-5.356	2.960	
	1483 216960.0 R10 1483 216960.0 R11	18 10	-4.353 2.059	2.352 37.009	4.990 29.719	-3.177 263.894	
Assure the start of the scale start	1483 216960.0 R11 1483 216960.0 R17	10	-4.159	-1.538	3.347	-0.778	
Nountpoint of the clock	1483 216960.0 R24	2	-4.234		-136.325	418.076	
•	1483 216961.0 GO2	23	3.392	0.016	0.426	-0.009	
corrections	1483 216961.0 GO6	61	1.263	0.726	0.937	0.123	
	1483 216961.0 GO7	35	-1.212	-0.007	0.855	-0.543	
	1483 216961.0 GO8	66	-7.025	1.471	-2.883	1.319	
	1483 216961.0 G10	39	5.639	0.729	2.267	0.509	
	1483 216961.0 G13	8	1.761	1.771	0.117	0.224	
	1483 216961.0 G15	3	0.035	0.110	0.362	0.009	
	1483 216961.0 G24	46	1.760	1.484	1.553	0.266	
	1483 216961.0 G25	106	3.586	0.843	-0.251	0.241	
	1483 216961.0 G26	70	-16.223	1.180	-0.810	0.199	
	1483 216961.0 G27	31	-0.925	0.806	-2.845	0.989	
	1483 216961.0 G28	171	8.476	1.517	-0.338	0.070	
	1483 216961.0 R07	18	-1.205	3.000	0.006	1.871	
	1483 216961.0 RO8 1483 216961.0 R10	18	-0.506	3.840	-5.356	2.960	
	1483 216961.0 RIU 1483 216961.0 R11	18 10	-4.353 2.058	2.352 37.005	4.991 29.730	-3.177 263.935	
	1483 216961.0 R11	10	-4.158	-1.544	3.348	-0.777	
	1483 216961.0 R24	2	-4.235		-136.375	418.095	
	1483 216962.0 GO2	23	3.393	0.016	0.426	-0.009	
	1483 216962.0 GO6	61	1.263	0.726	0.937	0.123	
EU	Drücken Sie F1, um die Hilfe aufz						2
	- ,		• •	-,			

26



Settings for the monitoring mountpoint decoder lat long nmea bytes 1 www.euref-ip.net:2101/GAIA0 RTGS 50.80 4.36 no 38.81 kb 2 www.euref-ip.net:2101/GAIA0 RTCM_2.3 41.11 351.41 no 86.006 kb 3 www.euref-ip.net:2101/GAIA0 RTCM_3.0 49.03 20.32 no 47.213 kb 06-06-10 12:15:37 ====================================		Proxy General RINEX Observations RINEX Observation rate 1 Hz • Failure threshold 0 min • Recovery threshold 0 min • Script (full path) D:/soehne/Realtime/Programe Performance log 1 min • Network monitoring, outages, handling of corrupted stress		Ephemeris Corrections Monitor
monitoring 2 www.euref-ip.net:2101/GAIA0 RTCM_2.3 41.11 351.41 no 86.006 kb 3 www.euref-ip.net:2101/GAIA0 RTCM_3.0 49.03 20.32 no 47.213 kb 08-06-10 12:15:37 ====================================		mountpoint	decoder lat long	nmea bytes
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3 www.euref-ip.net:2101/GANPO RTCM_3.0 49.03 20.32 no 47.213 kb 3 www.euref-ip.net:2101/GANPO RTCM_3.0 49.03 20.32 no 47.213 kb 08-06-10 12:15:37 ====================================	monitoring	2 www.euref-ip.net:2101/GAIA0	RTCM_2.3 41.11 351.41 r	no 86.006 kb
08-06-10 12:15:37 ====== Start BNC ====== 08-06-10 12:15:37 Get Data: CLCK1 in RTCM 3.x format 08-06-10 12:18:13 Get Data: BRU50 in RTIG5 format 08-06-10 12:18:13 Get Data: GATA0 in RTCM 2.x format 08-06-10 12:18:13 Get Data: GATA0 in RTCM 3.x format 08-06-10 12:18:13 Get Data: GATA0 in RTCM 3.x format 08-06-10 12:18:147 GANP0: Mean latency 1.37 sec, min 0.58, max 1.72, 32 epochs 08-06-10 12:18:46 GATA0: Mean latency 1.22 sec, min 0.49, max 3.25, 33 epochs 08-06-10 12:19:46 GATA0: Mean latency 1.96 sec, min 1.41, max 2.58, 33 epochs 08-06-10 12:19:46 GANP0: Mean latency 1.37 sec, min 0.58, max 1.73, 60 epochs 08-06-10 12:19:46 GANP0: Mean latency 1.99 sec, min 1.39, max 2.67, 60 epochs 08-06-10 12:19:46 GANP0: Mean latency 1.99 sec, min 0.57, max 1.63, 60 epochs 08-06-10 12:20:47 GATA0: Mean latency 1.32 sec, min 0.6, max 1.69, 60 epochs, 0 gaps		3 www.euref-ip.net:2101/GANPO	RTCM_3.0 49.03 20.32 r	no 47.213 kb
08-06-10 12:15:37 ====================================	showing latency and			
		08-06-10 12:15:37 Get Data: CLCK1 in RTCM 3.x format 98-06-10 12:18:13 ======= Start BNC ===== 08-06-10 12:18:13 Get Data: BRUS0 in RTIGS format 08-06-10 12:18:13 Get Data: GAIA0 in RTCM 2.x format 08-06-10 12:18:13 Get Data: GAIA0 in RTCM 3.x format 08-06-10 12:18:46 GAIA0: Mean latency 1.37 sec, min 0 08-06-10 12:18:47 GAIP0: Mean latency 1.22 sec, min 0 08-06-10 12:18:48 BRUS0: Mean latency 1.37 sec, min 1 08-06-10 12:19:46 GAIA0: Mean latency 1.37 sec, min 0 08-06-10 12:19:46 GAIA0: Mean latency 1.27 sec, min 0. 08-06-10 12:19:48 BRUS0: Mean latency 1.27 sec, min 0. 08-06-10 12:19:48 BRUS0: Mean latency 1.99 sec, min 1 08-06-10 12:20:46 GAIP0: Mean latency 1.14 sec, min 0 08-06-10 12:20:47 GAIA0: Mean latency 1.32 sec, min 0.	.58, max 1.72, 32 epochs .49, max 3.25, 33 epochs .41, max 2.58, 33 epochs .58, max 1.73, 60 epochs 47, max 2.67, 60 epochs .39, max 2.59, 60 epochs .5, max 1.63, 60 epochs, 0 gaps .6, max 1.69, 60 epochs, 0 gaps	
Add Mountpoints Delete Mountpoints Start Stop Help=Shift+F1		Add Mountpoints Delete Mountpoints Start Stop	Help=Shift+F1	

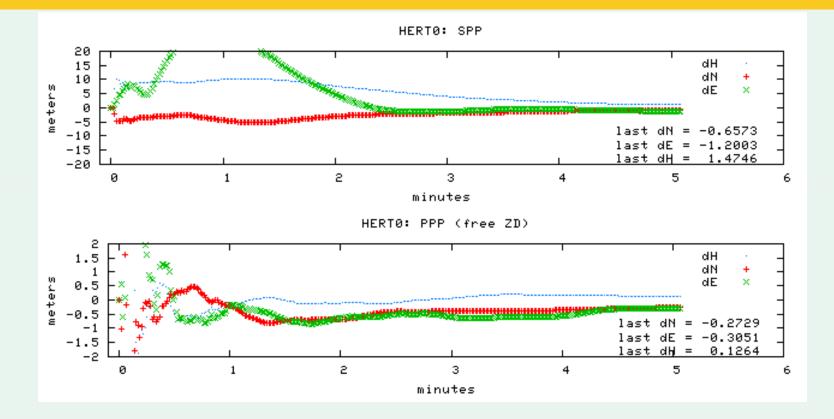


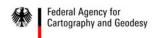
> RTNet

- By "GPS solutions" / L. Mervart
- Used for
 - either clock correction and ZTD estimation (network solution)
 - or coordinate estimation (PPP)
- Clock correction estimation successfully tested for Europe (GPS only and GPS+GLONASS), North America and Australia

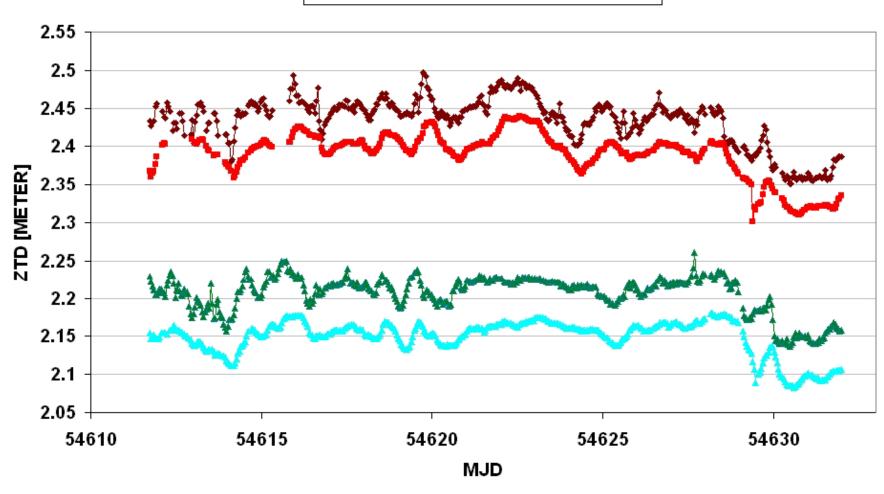


GNSS processing engine – results

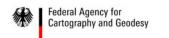




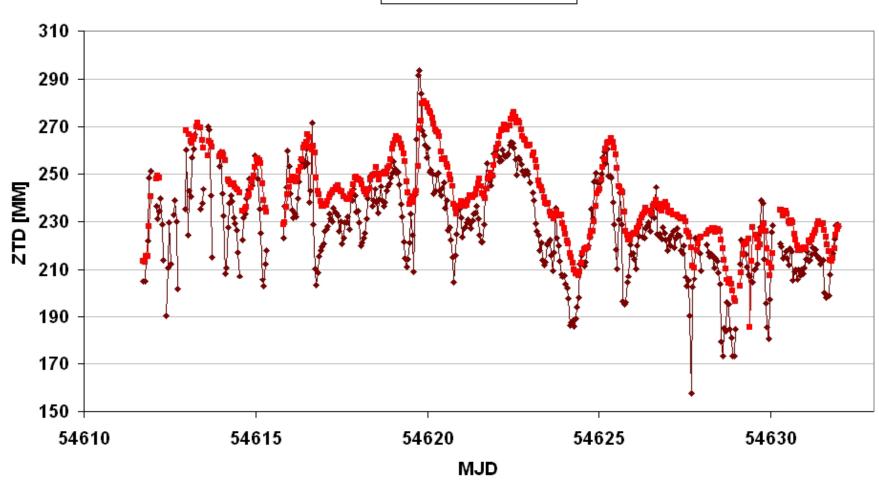




BSW_KARL — RTN_KARL — BSW_ZIMM — BSW_ZIM2



ZTD parameter from NRT with BSW5.0 (1h sampling) and RTNet (1 sec sampling)





- EPN real-time data streaming widely-used
- Moved to EPN routine operations
- Strategies of orbit and clock correction computation and dissemination is on an advanced level
- EUREF is going to launch a new SP about the enhancement of real-time data streams



Thank you for your attention!



Information & Downloads:

http://igs.bkg.bund.de

euref-ip@bkg.bund.de